## Methane Monitoring from Small Unmanned **Aerial Systems**

Lance E. Christensen, Vlad Manzatianu, Georgios Matheou Jet Propulsion Laboratory, The California Institute of Technology, Pasadena, CA

YangQuan Chen, Brendan Smith, Garrett John

Univ. of California - Merced, Merced, CA

California Methane Symposium Jun. 6-7, 2016

#### Point of contacts:

Lance Christensen (JPL) Carrie Greaney (PRCI)

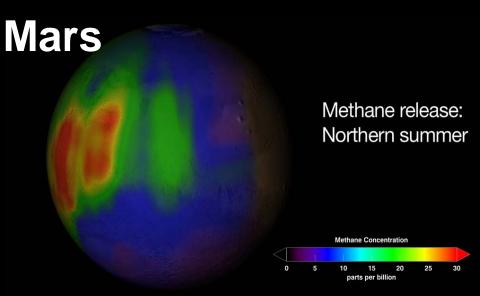
Lance.E.Christensen@jpl.nasa.gov cgreaney@prci.org

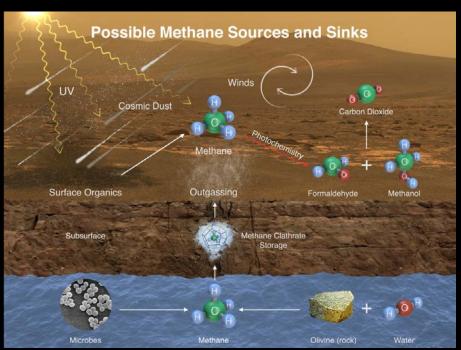






#### **Background**



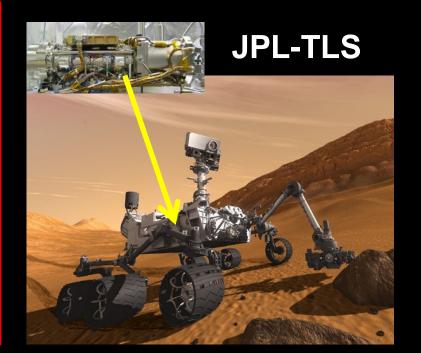


#### To get:



#### **Required NASA investment in:**

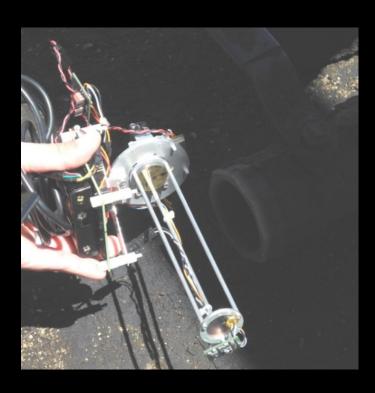
- Tunable laser spectrometers
- Semiconductor lasers



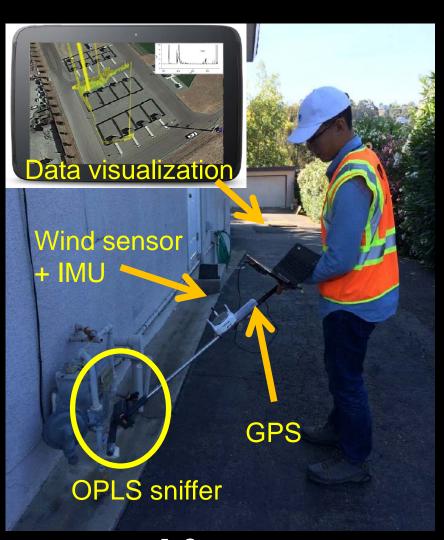
## Background

First, need a robust, miniature methane sensing instrument.

**Open-Path Laser Spectrometer (OPLS)** 



**Before** 



**After** 

## Vision: Pipeline & facilities



< 2.5 kg VTOL



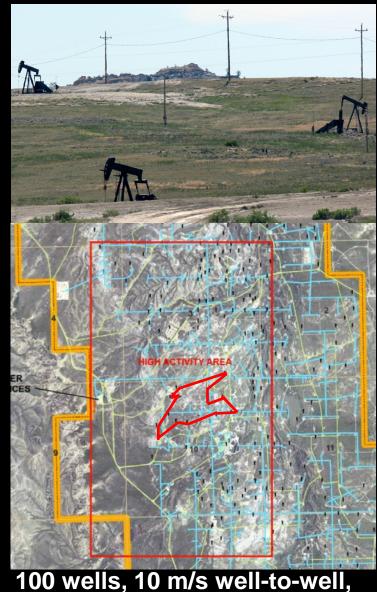
Fixed-wings & Hybrid fixed-wing/VTOL

#### **Types of operations:**

- Surveillance
- Localization
- Quantification

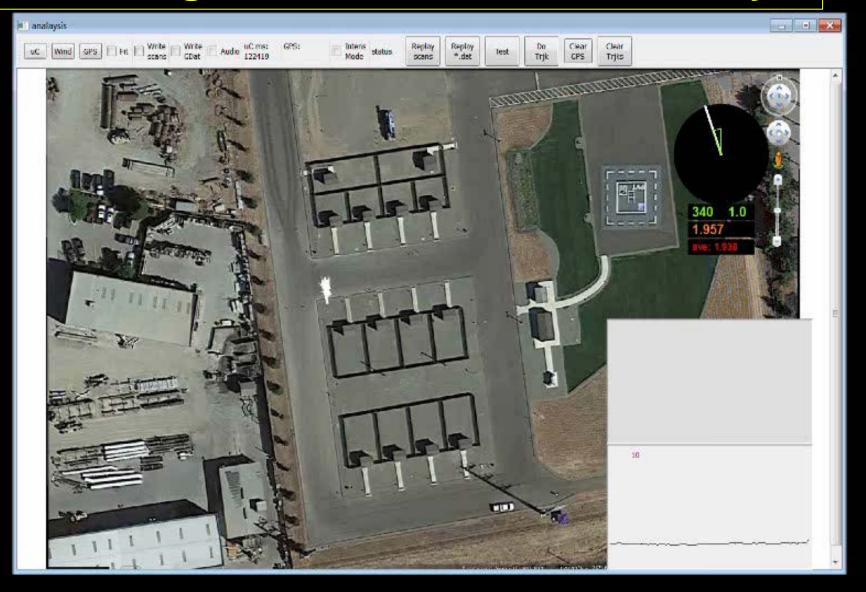
Movie\_A:Wells<u>Christensen\_movies\</u>
<a href="mailto:sim\_wells.mp4">sim\_wells.mp4</a>

#### **RMOTC Storage Facility**



100 wells, 10 m/s well-to-well, 30-s surveillance at each well → 40 wells per flight.

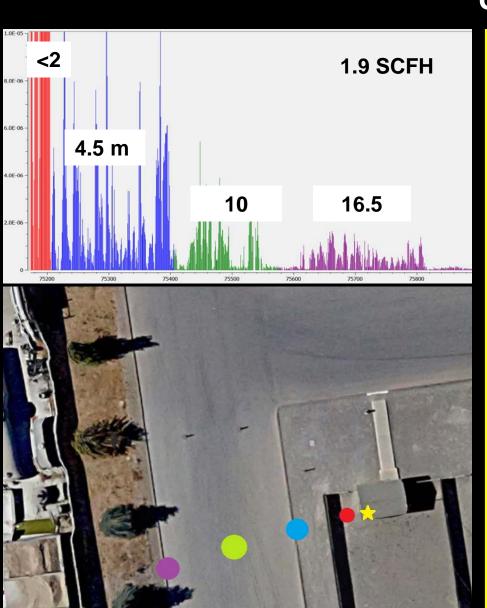
## Vision: Neighborhood sUAS leak survey



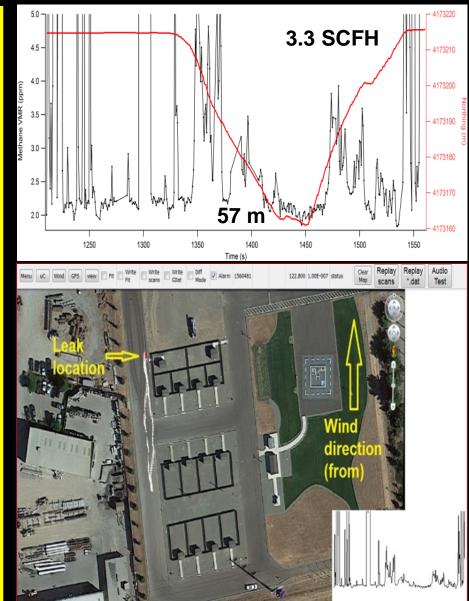
**Prescriptive operation** ≈ **Autonomous operation** 

#### **Performance** (×10<sup>-6</sup>) 0,80 0.85 0,90 0.95 1,00 inter-comparisons LGR OPLS 1 m/s 3500 -CH<sub>4</sub> VMR CH<sub>4</sub> VMR (ppm) 3000 2500 -2000 -1500 -1000 water 500 -...t응 (×10<sup>5</sup>) o,90 Time (s) 1.00 2.0 0.5 1.0 1.5 2.5 3.0 Time (s) Methane Methane 1000 Methane (ppm) Water 100 water 10 200 400 600 800 1000 1200 Time (s) Allan Variance (ppb<sup>2</sup>) Raw data 1.2 Hz 0.1 10 100 Time (s)

### **Data: Foot surveys**



# Learn behavior and signature of plumes in suburban setting



## **sUAS: Logistics**



Lockheed Indago at dry Lakebed and Caltech

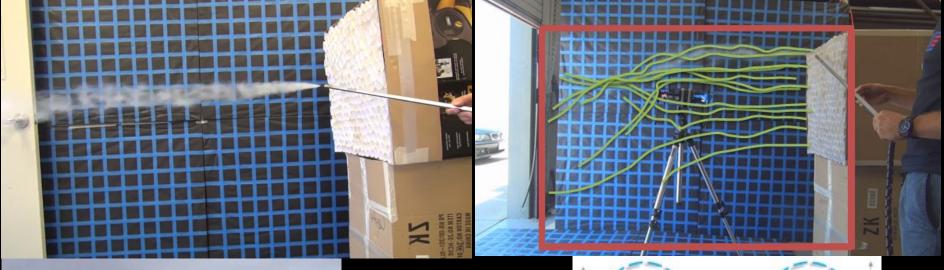




**3DR Iris at Merced grassland** 

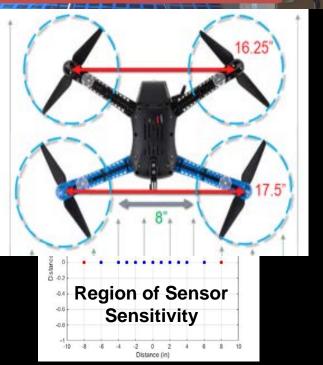
## sUAS: Prop-wash



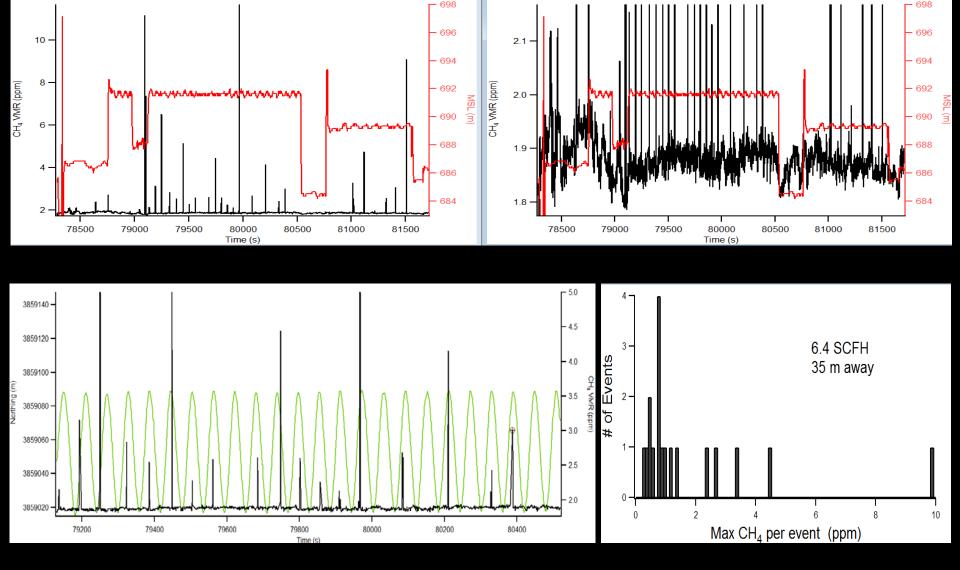




Flight test with smoke sensor

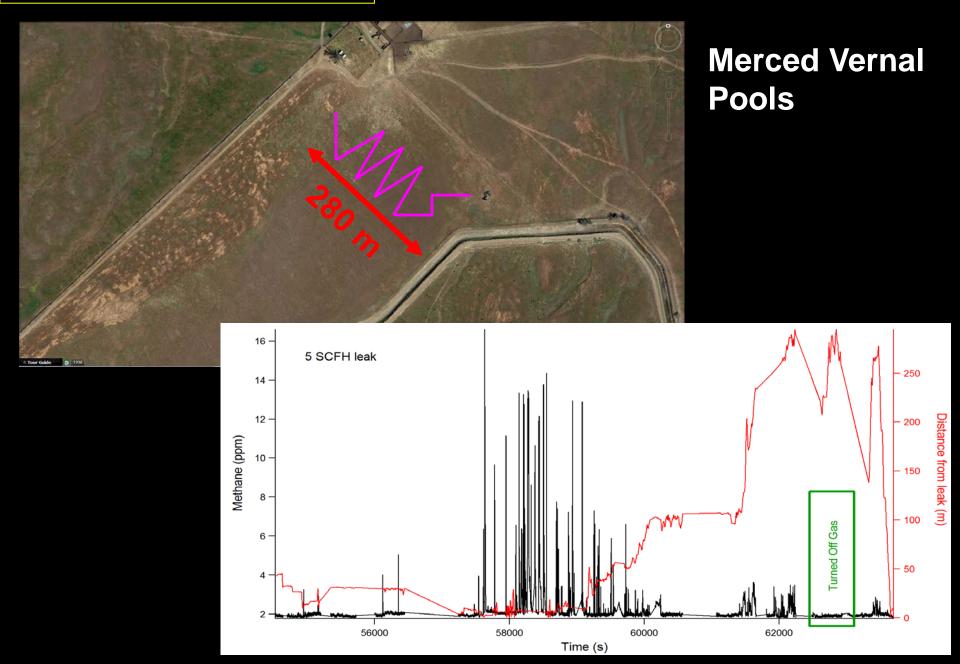


#### sUAS: Flight Data

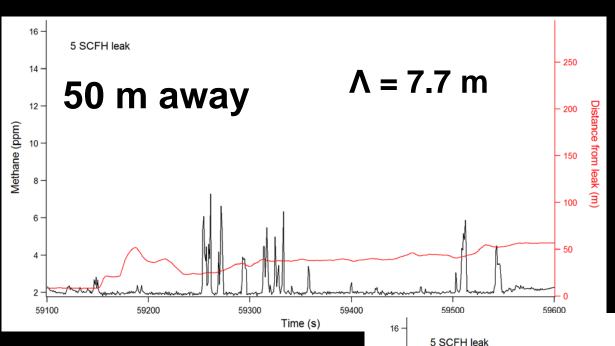


Movie\_B: OrbitalChristensen\_movies\orbit\_20151105\_backtraj.mp4

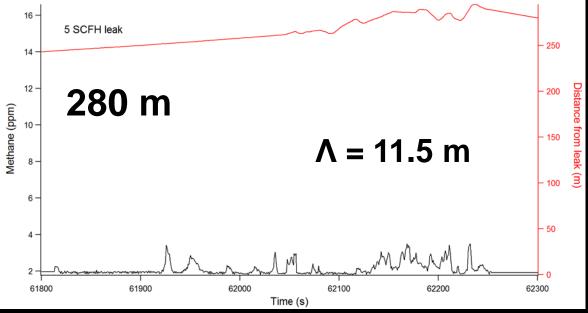
## **sUAS: Horizontal**



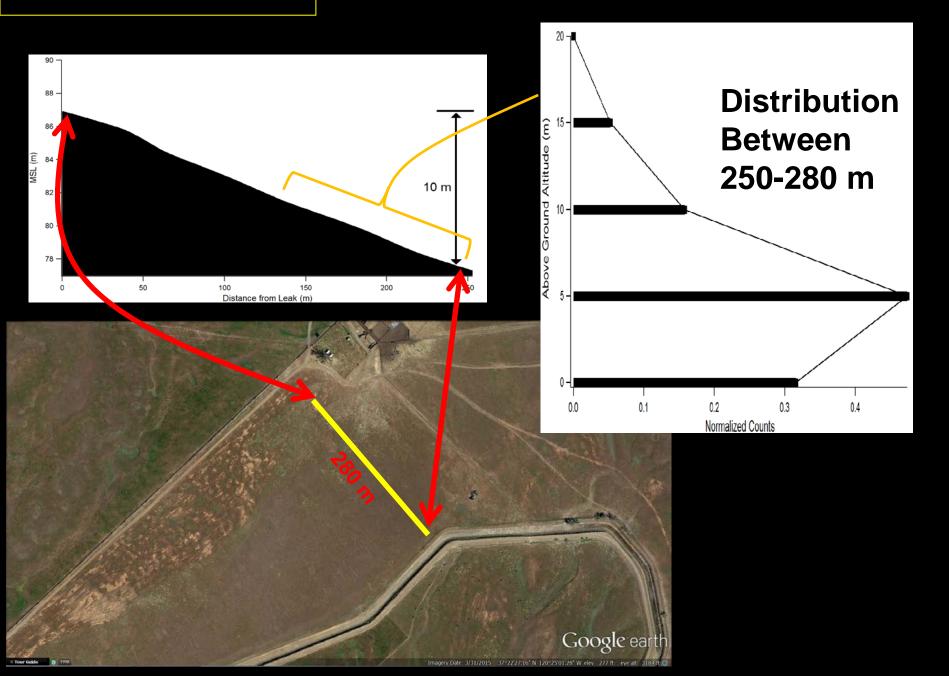
### **sUAS:** Horizontal



Define characteristic length, λ, as a measure of data 'sharpness'

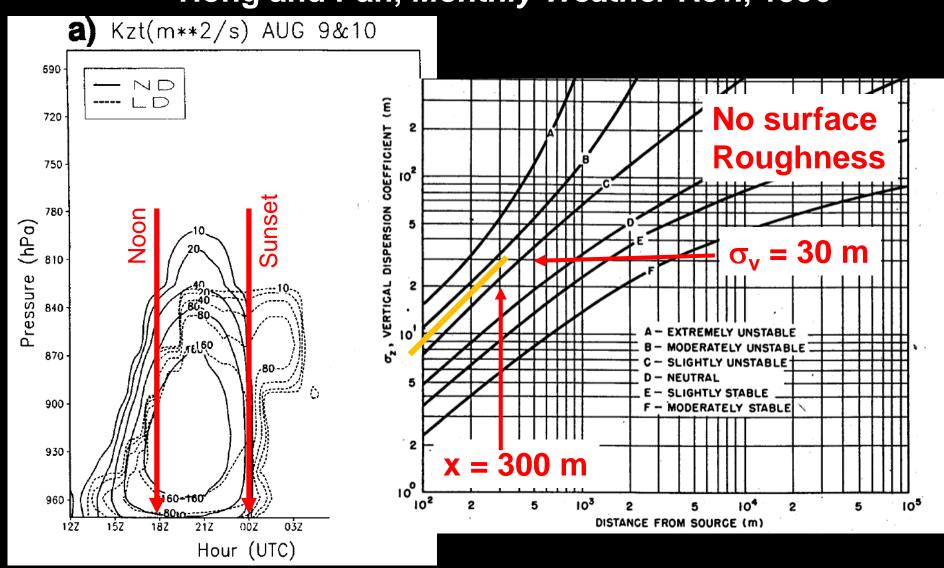


## **sUAS: Vertical**



#### **sUAS: Vertical**

#### Hong and Pan, Monthly Weather Rev., 1996



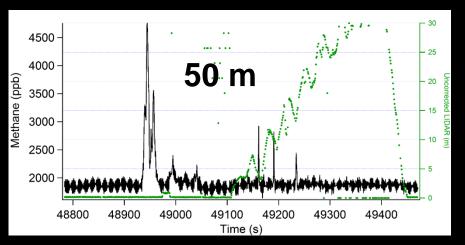
Vertical mixing during day

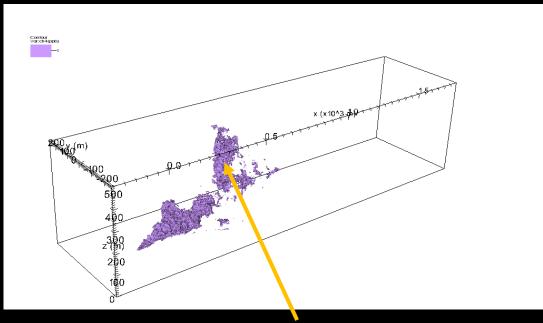
**Gaussian concentration profile** 

#### sUAS: Gaussian plume model insufficient

#### 2-m LES Modeling

- Convection
- Surface topology





Georgios Matheou (JPL) 5 m/s, mid-lat, noon, 6 SCFH. Passive scalar. Thermals are < 10% of area

Convection

#### Conclusions

- Flown OPLS on two different VTOLS < 2.5 kg</li>
  - Demonstrated 20 ppb s<sup>-1</sup> noise
  - 250 g OPLS
  - Expect plug-n-play system by end of 2016
- Building knowledge on how to deploy sUAS-OPLS
  - Right now, VTOLS; 2<sup>nd</sup> half of 2016, Fixed-wings/hybrids
  - Folding in understanding from LES modeling
    - convection
    - topology
  - Performing surveillance, localization, quantification